



Finding the Stars in the Fireworks: Deep Understanding of Motion Sensor Fingerprint

Huiqi Liu, Xiang-Yang Li, Lan Zhang, Yaochen Xie, Zhenan Wu, Qian Dai, Ge Chen, Chunxiao Wan

University of Science and Technology of China (USTC), Tencent

















Fingerprints Everywhere





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Device Fingerprint: An Example



Tracking exists in the real world!

Are you unique? Yes! (You can be tracked!)

38.68 % of observed browsers are Chrome, as yours.
1.54 % of observed browsers are Chrome 62.0, as yours.
13.65 % of observed browsers run Mac, as yours.
0.46 % of observed browsers run Mac 10.13, as yours.
63.52 % of observed browsers have set "en"as their primary language, as yours.
2.05 % of observed browsers have UTC+8 as their timezone, as yours.



Data Tracking





Privacy Leakage



4/17/18

Device Fingerprints Techniques



• How are device fingerprints generated?



We exploit small deviations in mobile devices from hardware.



• Smartphones are equipped with a wide range of sensors.





We focus on motion sensors to generate fingerprints.







What is Fingerprinting Capacity Model?

- The capacity means to estimate how many devices can be distinguished by their manufacturing variances.
- It is a theoretical (mathematical) model to estimate the capacity of motion sensor fingerprint.





Fingerprinting Capacity

What is the capacity of device fingerprint? **The model, analysis and feature.**



Fingerprinting Factors

Which factor infects the fingerprint most? The user activity, device brand or device model.

De-fingerprinting Trade-off

How to anonymize sensor data while retaining utility?









Capacity Model



- We treat the fingerprinting problem as a classification problem.
 - For 'bin', we use the classification layer as the feature space.
 - For 'ball', each data piece of a device is treated as a ball.
 - For 'dimension', two sensors (accelerometer and gyroscope) can be treated as independent dimensions for device fingerprint.







• With users' permission, we collect motion sensor (accelerometer and gyroscope) data from **total 117 mobile phones** with 13 different brands.



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The expectation of collided devices are increasing when the number of devices increases in our experiments.



The expectation=0.38 when the device number=117 This is consistent with our experiment result that for 117 devices given 20 seconds data of each devices the fingerprinting accuracy is 99%.



The expectation and the probability of indistinguishable devices.



For more than 200 devices, there is expected to be at least two collisions.









Fingerprinting Capacity

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• Influence of Static vs. Dynamic

On flat surface	State-of-the-art	93 Devices	96%
	Our Work	97 Devices	97%
Arbitrary	State-of-the-art	117 Devices	77%
human motion	Our Work	117 Devices	91%
Mixed data	State-of-the-art	117 Devices	80%
	Our Work	117 Devices	92%
	Our Work	117 Devices with majority voting)99%

Fingerprinting Analysis Cont'd



- Sensors and axes
 - First, we conduct LSTM-based fingerprinting on each sensor's data separately.
 - Each sensor has three axes, we fingerprint three axes of each sensor separately.



Fingerprinting Analysis Cont'd



• Influence of brands, models and human



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Fingerprinting Capacity

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Fingerprinting Factors

Which factor infects the fingerprint most? The user activity, device brand or device model.

De-fingerprinting Trade-off

How to **anonymize** sensor data while retaining **utility**?



Anonymization effect

• Fingerprinting model result

Data utility

- L2 distance
- Step counter result





De-fingerprinting (anonymization) Analysis











- We propose a theoretical model to understand the capacity of fingerprinting, it is a primary work and can be also used in other scenarios.
- We design a deep neural network based model to fingerprint mobile device sensors in real-life uses.
- We propose a novel generative model to anonymize sensor data while retaining good data utility, but it is still needed to deeply investigate that how vulnerable are the de-fingerprinting models against different types of fingerprinting attacks.

Datasets



- Our dataset is available, PLEASE feel free to DOWNLOAD it for fingerprinting research.
- Link: <u>https://drive.google.com/open?id=14eYWdB-</u> 77NMUCui4MZQPxpbjwZeNLi94

Introduction

For each motion sensor, i.e., accelerometer or gyroscope, three data sequences are simultaneously generated with with timestamps by three axes. So, in our experiments, we obtain 6 data sequences from two motion sensors. Each sequence can be a channel of the neural network input. However, they are generated with unstable time intervals, which depends on the schedule of the mobile operating system according to the real-time system load. Hence, we conduct piecewise cubic Hermite interpolation to obtain equally spaced data sequences as the inputs of neural networks. We divide continuous sensor data into 0.5~20-second segments as our dataset.

Data format

Recommanded method to load the dataset:

```
with gzip.open(filename, 'rb') as f:
    dataset = pickle.load(f)
    data = dataset['data']
    label = dataset['label']
```

Each file follows the format:

```
# dataset
{
    # data, shape (number of pieces, number of sample points, 3 axes, 2 sensors)
    'data': []
    # label, shape (number of pieces, )
    'label': []
```





nank you for listening~

• Huiqi Liu

- liuhuiqi@mail.ustc.edu.cn
- https://charlesliu7.github.io/